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- random variables and their distributions
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- expectation, variance, covariance
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Too much material! Some of these slides will be skipped in lecture, but are included so you can look them over later.

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#### Discrete probability:

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- We abbreviate  $\mathbb{P}(\{\omega\})$  as  $\mathbb{P}(\omega)$ .

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- Why did Kolmogorov need to set up a probability space? Answer: to unify probability with the rest of mathematics.

We can derive facts from the probability axioms:

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- ► Generalized Inclusion-Exclusion:  $\mathbb{P}(\bigcup_{i=1}^{n} A_i) = \sum_{i=1}^{n} (-1)^{n+1} \sum_{S \subseteq \{1,...,n\}, |S|=i} \mathbb{P}(\bigcap_{i \in S} A_i).$

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- ▶ Note: In probability,  $\mathbb{P}(A \cap B)$  is abbreviated as  $\mathbb{P}(A, B)$ .

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- ▶ "Divide and conquer" strategy for calculating  $\mathbb{P}(A)$ .

If  $B_1, ..., B_n$  are possible causes, and A is the effect, then for each i = 1, ..., n,

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#### Random Variables

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- ▶ Similarly, for  $A \subseteq \mathbb{R}$ ,  $\{X \in A\}$  is the event  $X^{-1}(A)$ .
- ▶ Abbreviate  $\mathbb{P}(\{X = x\})$  as  $\mathbb{P}(X = x)$ .

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- Give a named distribution with parameters.

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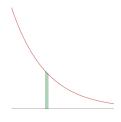
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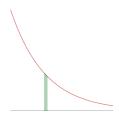
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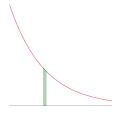


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- ▶ (both discrete) the joint PMF  $p_{X,Y}(x,y) := \mathbb{P}(X = x, Y = y)$ ;
- ▶ (both continuous) the joint PDF  $f_{X,Y}: \mathbb{R}^2 \to \mathbb{R}_{\geq 0}$  such that  $\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f_{X,Y}(x,y) dx dy = 1$ .

The definitions extend for more than two RVs.

The notation 
$$\mathbb{P}(X = x, Y = y)$$
 is shorthand for  $\mathbb{P}(\{X = x\} \cap \{Y = y\}) = \mathbb{P}(\{\omega \in \Omega : X(\omega) = x \text{ and } Y(\omega) = y\}).$ 

How to calculate probabilities: for  $A \subseteq \mathbb{R}^2$ ,

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Example where *X* and *Y* take on two values each:

$$y = 0$$
  $y = 1$   $p_X$   
 $x = 0$   $p_{X,Y}(0,0) = 0.1$   $p_{X,Y}(0,1) = 0.3$   $p_X(0) = 0.4$   
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- From the joint, we can recover the marginals.
- From the marginals of *X* and *Y*, we do not have enough information to recover the joint.

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### Bayes Rule for RVs

X is  $\mathbb{Z}$ -valued. Y is  $\mathbb{Z}$ -valued:

$$p_{X|Y}(x \mid y) = \frac{p_X(x)p_{Y|X}(y \mid x)}{p_Y(y)} = \frac{p_X(x)p_{Y|X}(y \mid x)}{\sum_{x'=-\infty}^{\infty} p_X(x')p_{Y|X}(y \mid x')}$$

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- So if  $X_1, ..., X_n$  are independent,  $\operatorname{var} \sum_{i=1}^n X_i = \sum_{i=1}^n \operatorname{var} X_i$ .

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- Example: Pick a permutation of  $\{1, ..., n\}$  uniformly at random; X is the number of fixed points. For i = 1, ..., n,  $X_i$  indicates if the ith position is fixed, so  $X = \sum_{i=1}^{n} X_i$ .

### Discrete Distributions Reference

#### Bernoulli(p) ( $p \in [0,1]$ ):

► Same as Binomial(1,*p*).

### Binomial(n,p) $(n \in \mathbb{Z}^+, p \in [0,1])$ :

► PMF: 
$$p_X(x) = \binom{n}{x} p^x (1-p)^{n-x}$$
 for  $x \in \{0,1,...,n\}$ .

▶ 
$$\mathbb{E}[X] = np$$
, var  $X = np(1-p)$ .

### Geometric(p) ( $p \in (0,1]$ ):

▶ PMF: 
$$p_X(x) = p(1-p)^{x-1}$$
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• 
$$\mathbb{E}[X] = 1/p$$
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### Poisson( $\lambda$ ) ( $\lambda \in (0, \infty)$ ):

▶ PMF: 
$$p_X(x) = \exp(-\lambda)\lambda^x/x!$$
 for  $x \in \mathbb{N}$ .

$$ightharpoonup \mathbb{E}[X] = \lambda$$
, var  $X = \lambda$ .

### Continuous Distributions Reference

#### Uniform([a,b]) ( $-\infty < a < b < \infty$ ):

- ▶ PDF:  $f_X(x) = 1/(b-a)$  for  $x \in [a,b]$ .
- $ightharpoonup \mathbb{E}[X] = (a+b)/2$ , var  $X = (b-a)^2/12$ .

### Exponential( $\lambda$ ) ( $\lambda \in (0, \infty)$ ):

- ▶ PDF:  $f_X(x) = \lambda \exp(-\lambda x)$  for  $x \ge 0$ .
- $ightharpoonup \mathbb{E}[X] = 1/\lambda$ , var  $X = 1/\lambda^2$ .

### Normal( $\mu$ , $\sigma^2$ ) ( $\mu \in \mathbb{R}$ , $\sigma^2 \ge 0$ ):

- ► PDF:  $f_X(x) = (2\pi\sigma^2)^{-1/2} \exp[-(x-\mu)^2/(2\sigma^2)].$
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Sum of independent Poisson:  $X \sim \text{Poisson}(\lambda)$ ,  $Y \sim \text{Poisson}(\mu)$  are independent; show  $X + Y \sim \text{Poisson}(\lambda + \mu)$ .

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- Key idea: Use Law of Total Probability.
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(X, Y) is uniformly distributed on the unit square; the probability is the shaded area (9/16).

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- Calculate:  $\mathbb{E}[\bar{X}_n] = \mu$  and  $\operatorname{var} \bar{X}_n = \sigma^2/n$ .
- ▶ Variance shrinks with *n*. By Chebyshev,  $\mathbb{P}(|\bar{X}_n \mu| \ge \varepsilon) \to 0$  as  $n \to \infty$ .

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#### What is the use of the WLLN?

- ▶ Suppose we do not know  $\mu$ .
- If we collect enough samples (n is large), then  $\bar{X}_n$  is basically the same thing as  $\mu$ .

Given n samples and  $\delta > 0$ , a  $1 - \delta$  confidence interval for  $\mu$  is a random interval  $(\bar{X}_n - \varepsilon, \bar{X}_n + \varepsilon)$  so that with probability  $\geq 1 - \delta$ ,  $\mu$  lies in the interval.

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- You will be given two out of the three: n,  $\delta$ ,  $\varepsilon$ . Solve for the quantity you are not given.

From the WLLN, we know that if we add  $X_1, ..., X_n$  and divide by n, then we lose almost all information about the distribution: for large n,  $(\sum_{i=1}^{n} X_i)/n$  is basically a constant,  $\mu$ .

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- ▶ Central Limit Theorem (CLT): As  $n \to \infty$ ,  $Z_n$  converges in distribution to Normal(0, $\sigma^2$ ), in the sense that

$$\mathbb{P}(Z_n \leq z) \to \int_{-\infty}^{z} \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{x^2}{2\sigma^2}\right) dx.$$

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Markov Property: For all  $n \in \mathbb{N}$  and feasible sequences of states  $i_0, i_1, \dots, i_{n-1}, i, j$ ,

$$\mathbb{P}(X_{n+1} = j \mid X_n = i, X_{n-1} = i_{n-1}, \dots, X_1 = i_1, X_0 = i_0)$$

does *not* depend on  $i_0, i_1, \dots, i_{n-1}$  and n.

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- ▶ We call this quantity P(i,j) and we put it in the (i,j) entry of an  $|S| \times |S|$  transition probability matrix P.

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- ▶ In matrix notation,  $\pi_1 = \pi_0 P$ .
- Hitting the distribution vector by the transition matrix advances the dynamics by one step!

The distribution of  $X_0$  is called the *initial distribution*.

- ► To discuss the distributions of  $(X_n)_{n \in \mathbb{N}}$ , we use different notation. For all  $n \in \mathbb{N}$  and  $i \in S$ ,  $\pi_n(i) := \mathbb{P}(X_n = i)$ .
- ▶ We think of  $\pi_n$  as a *row vector* (of length |S|).
- ▶ Quick quiz: is  $\pi_n$  a random variable? No!

#### Transition of distribution:

- ▶ In matrix notation,  $\pi_1 = \pi_0 P$ .
- ► Hitting the distribution vector by the transition matrix advances the dynamics by one step!
- ▶ Then,  $\pi_n = \pi_0 P^n$ .

Hitting time: What is the expected time to hit state  $j \in S$ ?

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Probability of hitting *A* before *B*: Let  $A, B \subseteq S$ . What is the probability of hitting *A* before *B*?

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- Again, solve the system of linear equations.

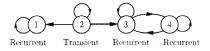


Figure: Figure taken from *Introduction to Probability* by Bertsekas and Tsitsiklis, 2nd edition.

A *class* is a set of states in which every state can talk to any other state.

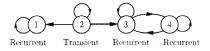


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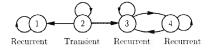


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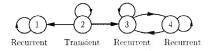


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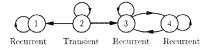


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The probability mass "leaks out of" transient classes and remains in recurrent classes. Therefore, only recurrent classes matter for long-term Markov chain behavior.

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Stationary distribution: The probability distribution  $\pi$  (a row vector) is called a *stationary (or invariant) distribution* if  $\pi = \pi P$ .

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- Every Markov chain has at least one stationary distribution.
- ► If the Markov chain is irreducible, the stationary distribution is unique.

MC Law of Large Numbers: If  $(X_n)_{n\in\mathbb{N}}$  is an irreducible MC, then for any state  $i\in S$  and any  $\pi_0$ ,  $n^{-1}\sum_{m=0}^{n-1}\mathbbm{1}_{\{X_m=i\}}$  converges, as  $n\to\infty$ , to  $\pi(i)$ , where  $\pi$  is the stationary distribution.

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Do the distributions themselves converge?

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MC Convergence Theorem: If the MC  $(X_n)_{n\in\mathbb{N}}$  is irreducible and aperiodic, then  $\pi_n\to\pi$  as  $n\to\infty$ . In other words,  $\mathbb{P}(X_n=i)\to\pi(i)$  as  $n\to\infty$  for every  $i\in S$ .

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- ▶ The theorem holds, *regardless of the initial distribution*  $\pi_0$ .
- If the chain is periodic, then convergence can still happen for some initial distributions.

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Nevertheless, they may still help you practice the concepts of discrete math/probability.